ADMISSIBILITY AND OPTIMALITY OF EXPERIMENTAL DESIGNS

Norbert Gaffke and Friedrich Pukelsheim Institut für Mathematik der Universität Augsburg

1. INTRODUCTION

In this paper we study the relation between admissibility and optimality of experimental designs. While it is standard decision theoretic reasoning that a statistical procedure which is uniquely optimal will necessarily be admissible, we here prove a converse to the effect that an admissible design is uniquely optimal with respect to the E-criterion and a specific choice of the parameter system of interest. The general equivalence theory may then be employed to obtain necessary conditions for admissibility.

As usual we choose the experimental conditions from a compact k-dimensional experimental domain $\mathcal{X} \subset \mathbb{R}^k$. We assume that under experimental conditions $x \in \mathcal{X}$ the real observation Y(x) follows a linear model

$$Y(x) = x'\theta + \sigma e(x)$$

with uncorrelated errors e(x) of unit variance. A design ξ is a probability distribution with finite support on the experimental domain \mathcal{X} , determining allocation and proportion of the experimental conditions.

The performance of a design ξ is determined through its $k \times k$ moment matrix

$$M(\xi) = \int_{\mathcal{X}} x x' d\xi.$$

Let M be the feasible set of moment matrices, assumed to be a convex and compact subset of nonnegative definite $k \times k$ matrices.

We shall study admissibility of a candidate matrix M in the set M. It is illuminating to first discuss the case when the full parameter θ is of interest (Section 2). Before turning to the more general case of an s-dimensional parameter system $K'\theta$ (Section 4) we derive some intermediate results on information matrices (Section 3).

2. ADMISSIBILITY FOR THE FULL PARAMETER SET

Suppose $M \in \mathcal{M}$ is a moment matrix whose admissibility properties we wish to investigate. We call M admissible for θ in \mathcal{M} when no moment matrix $A \in \mathcal{M}$ satisfies $A \geq M$ and $A \neq M$, relative to the Löwner ordering \geq . To avoid trivialities we assume $M \neq 0$.

We shall show that every admissible moment matrix is E-optimal, i.e. it maximizes the minimum eigenvalue of an appropriate information matrix. However, the parameter system for which E-optimality is obtained is related to the candidate matrix M in an intrinsic manner: We choose the system $H'\theta$ from a full rank decomposition

$$M = HH'$$

where with $r = \operatorname{rank} M$ the $k \times r$ matrix H has full column rank r. An E-optimal moment matrix for $H'\theta$ in M is one which maximizes $\lambda_{\min}(C_H(A))$ over $A \in \mathcal{M} \cap \mathcal{A}(H)$, where $\mathcal{A}(H)$ is the convex cone of all nonnegative definite $k \times k$ matrices whose range contains the range of H, and

$$C_H(A) = (H'A^-H)^{-1}$$
 for $A \in \mathcal{A}(K)$.

We need an auxiliary lemma before turning to admissibility.

Lemma 1. Let $A \in M$ be a competing moment matrix. If A is E-optimal for $H'\theta$ in M then $A \geq M$.

Proof. By construction the range of M contains (actually coincides with) the range of H, and we have

$$C_H(M) = (H'M^-H)^{-1} = (H'(HH')^-H)^{-1} = I_r.$$

Optimality of A yields $1 = \lambda_{\min}(C_H(M)) \leq \lambda_{\min}(C_H(A))$. Therefore $I_r \leq C_H(A)$, and pre- and postmultiplication with H and H' gives

$$M = HH' \leq HC_H(A)H' \leq A$$

where the last inequality may be found for instance in Pukelsheim & Styan (1983, p. 147).

We are now in a position to establish the relation between admissibility and unique *E*-optimality as announced above.

Theorem 1. The moment matrix M is admissible for θ in M if and only if M is uniquely E-optimal for $H'\theta$ in M.

Proof. Suppose M is admissible. From Theorem 2 in Pukelsheim (1980, p. 344) we know that there exists an E-optimal moment matrix A for $H'\theta$ in M. By Lemma 1 we have $A \geq M$, and admissibility of M forces A = M. This establishes unique E-optimality of M.

Conversely suppose M is uniquely E-optimal. Let A be a competing moment matrix satisfying $A \geq M$. Due to monotonicity A will also be E-optimal. But then uniqueness forces A = M, i.e. admissibility of M.

Lemma 1 and Theorem 1 are closely related to Corollary 8.4 of Pukelsheim (1980, p. 359). Next we turn to the classical Theorem 7.1 on admissibility of Karlin & Studden (1966, p. 808), investigating the existence of a nonnegative definite matrix $N \neq 0$ or a positive definite matrix N satisfying the system of normality inequalities

$$\operatorname{trace}(AN) \leq \operatorname{trace}(MN)$$
 for all $A \in M$.

Employing customary notions of convex analysis we shall call a matrix N which satisfies this system of inequalities to be normal to M at M.

Theorem 2. (i) If M is admissible for θ in M then there exists a nonnegative definite $k \times k$ matrix $N \neq 0$ which is normal to M at M.

(ii) If there exists a positive definite $k \times k$ matrix N which is normal to M at M then M is admissible for θ in M.

Proof. (i) From Theorem 1 we know that M is E-optimal for $H'\theta$ in M. The general equivalence theory provides a necessary and sufficient condition of optimality in the following form, see Theorem 8 of Pukelsheim (1980, p. 356). Optimality holds if and only if for all $A \in \mathcal{M}$

$$\operatorname{trace}\left(H'GAG'HE\right) \leq \lambda_{\max}(H'M^{-}H) = 1/\lambda_{\min}(C_{H}(M)),$$

for some generalized inverse G of M and some matrix $E \in \operatorname{conv} S$. Here $\operatorname{conv} S$ denotes the convex hull of all $r \times r$ matrices of the form zz' such that z is a normalized eigenvector of $C_H(M)$ corresponding to $\lambda_{\min}(C_H(M))$. However, we have seen above that $C_H(M) = I_r$, and so E actually is an arbitrary nonnegative definite $r \times r$ matrix with trace equal to 1.

Define the nonnegative definite matrix N = G'HEH'G. Then

$$\operatorname{trace} AN \leq 1 = \operatorname{trace} MN \quad \text{ for all } A \in \mathcal{M}.$$

Hence N cannot be 0, and it satisfies the normality inequalities.

(ii) Let A be a competing moment matrix satisfying $A \geq M$. Then $0 \leq \operatorname{trace} \{(A - M)\}$ N On the other hand the normality inequalities yield trace $\{(A-M)N\} \leq 0$. Therefore trace $\{(A-M)N\}=0$, and positive definiteness of N forces A=M. Thus admissibility is established.

Our proof provides the additional information that in Theorem 2(i) we can choose N so as to satisfy $1 \leq \operatorname{rank} N \leq r = \operatorname{rank} M$.

Note that rank 1 matrices M=cc' may well be admissible for the k-dimensional parameter θ . By Theorem 1 admissibility then holds if and only if M is uniquely optimal for $c'\theta$ in M, and then Theorem 2(i) admits a rank 1 choice N=dd'.

Admissibility for a subset of the full parameter system admits a similar development, with slightly more technical input concerning information matrices.

3. INFORMATION MATRICES

Consider a fixed s-dimensional parameter system $K'\theta$ given by some $k \times s$ matrix Kof full comlumn rank s. Admissibility for $K'\theta$ concentrates on the $s \times s$ information matrix for $K'\theta$ which, if $A \in \mathcal{A}(K)$ with $\mathcal{A}(K)$ defined as in the preceding section, is given by

$$C_K(A) = (K'A^-K)^{-1}.$$

Recall that for the full parameter case a rank deficient moment matrix M may be admissible. Similarly a rank deficient information matrix $C_K(A)$ may prove admissible for $K'\theta$, provided we exercise some care when extending the matrix function C_K from $\mathcal{A}(K)$ to the convex cone NND(k) of all nonnegative definite k imes k matrices. The appropriate definition for an arbitrary matrix $A \in NND(k)$ is

$$C_K(A) = \lim_{\epsilon \downarrow 0} (K'(A + \epsilon I)^{-1}K)^{-1}.$$

Then $C_K(A)$ is nonsingular if and only if $A \in \mathcal{A}(K)$ and in this case

$$C_K(A) = (K'A^-K)^{-1},$$

see Lemma 2 in Müller-Funk, Pukelsheim & Witting (1985, p. 23). Another representation of the extended matrix function C_K was used in Gaffke (1987), namely

$$C_K(A) = \min_{L_K} L_K A L_K',$$

where the minimum is taken over all left inverses L_K of K (i.e. $L_KK = I_s$) and is carried out relative to the Löwner matrix ordering. That the minimum exists is a consequence of the Theorem in Krafft (1983). It can also be seen using the Gauss-Markov Theorem, as follows.

Consider a linear model with expectation $K\beta$ and dispersion matrix A, where $\beta \in \mathbb{R}^s$ is the unknown parameter vector. The set $\{L_K\}$ of left inverses of K defines the set of linear unbiased estimators for β , and the BLUE for β corresponds to a particular member L_K such that L_KAL_K' is a minimum. We will call such a matrix L_K a left inverse of K minimizing for A, i.e.

$$L_K K = I_s$$
 and $C_K(A) = L_K A L'_K$.

Equivalently one could say that L'_K is a minimum A-seminorm generalized inverse of K', see Rao & Mitra (1971, p. 46).

Both expressions for $C_K(A)$ coincide, as shown next.

Lemma 2. For all nonnegative definite $k \times k$ matrices A we have

$$\lim_{\epsilon \downarrow 0} (K'(A+\epsilon I)^{-1})^{-1} = \min_{L_K} L_K A L'_K.$$

Proof. Since for $\epsilon > 0$ the matrix $A + \epsilon I$ is positive definite, we know from the Gauss-Markov Theorem that

$$\min_{L_K} L_K(A + \epsilon I) L_K' = (K'(A + \epsilon I)^{-1}K)^{-1}.$$

Let L_K^* be a left inverse of K minimizing for A. Then

$$\min_{L_K} L_K A L_K' \leq \min_{L_K} L_K (A + \epsilon I) L_K' \leq L_K^* (A + \epsilon I) L_K^{*l},$$

and letting $\epsilon \to 0$ the assertion follows.

With the extended definition of C_K a moment matrix $M \in \mathcal{M}$ is called admissible for $K'\theta$ in \mathcal{M} when no moment matrix $A \in \mathcal{M}$ satisfies $C_K(A) \geq C_K(M)$ and $C_K(A) \neq C_K(M)$.

Again we wish to study a fixed moment matrix $M \in M$. However, we now choose a full rank decomposition of its information matrix (which we assume to be nonzero)

$$C_K(M) = HH',$$

where with $t = \operatorname{rank} C_K(M)$ the $s \times t$ matrix H has full column rank t.

We shall have to investigate the parameter system $H'K'\theta$. The information matrices relative to the representations $(KH)'\theta$ and $H'(K'\theta)$ satisfy the following decomposition rule. The matrix functions C_{KH} and C_{H} are defined as above with KH and H instead of K and with domains NND(k) and NND(s), respectively.

Lemma 3. For all nonnegative definite $k \times k$ matrices A we have

$$C_{KH}(\mathbf{A}) = C_H(C_K(\mathbf{A})).$$

Proof. When A is positive definite then

When
$$A$$
 is positive definite then $C_K(A) = (H'K'A^{-1}KH)^{-1} = C_H((K'A^{-1}K)^{-1}) = C_H(C_K(A)).$

Now take a nonnegative definite matrix A. For $\epsilon > 0$ then $C_K(A) \leq C_K(A + \epsilon I)$. Since $A + \epsilon I$ is positive definite we obtain $C_H(C_K(A)) \leq C_{KH}(A + \epsilon I)$. The right hand side

For the converse inequality let L_H be a left inverse of H minimizing for $C_K(A)$, becomes $C_{KH}(A)$ when $\epsilon \to 0$. and L_K be a left inverse of K minimizing for A. Obviously $L_H L_K$ is a left inverse of KH, and by Lemma 2

Lemma 2
$$C_{KH}(A) \leq L_H L_K A L'_K L'_H = L_H C_K(A) L'_H = C_H(C_K(A)).$$

The two inequalities force equality, and the proof is complete.

An analoguous decomposition rule holds for left inverses of KH minimizing for A.

Lemma 4. A left inverse L_{KH} of KH is minimizing for A if and only if $L_{KH} = L_H L_K$ for some left inverse L_K of K minimizing for A and some left inverse L_H of H mini-

Proof. We first note that if L_K is a given left inverse of K, then the set of all left inverses of K is the linear manifold L_K+B where B may be any $s \times k$ matrix with BK=0. From this it is easy to see that L_K is minimizing for A if and only if $L_KAQ_K=0,$ where Q_K denotes the orthogonal projector onto the nullspace of K'.Similarly a left inverse L_{KH} of KH is minimizing for A if and only if $L_{KH}AQ_{KH}=0$, where Q_{KH} is the orthogonal projector onto the nullspace of (KH)'.

To prove the direct part of the lemma let L_{KH} be a left inverse of KH minimizing for A. Consider the matrix equations

the matrix equations
$$L_{KH}KX = L_{KH}$$
, and $X \cdot [K, AQ_K] = [I_s, 0]$.

Obvioulsy each of them separately has a solution. Moreover they have a common solution for X, by Theorem 2.3.3 in Rao & Mitra (1971, p. 25). In order to apply this theorem we must verify $L_{KH}K[I_s,0]=L_{KH}[K,AQ_K]$, but this holds true in view of $L_{KH}AQ_{KH}=0$ and $Q_K=Q_{KH}Q_K$. Setting $L_K=X$ and $L_H=L_{KH}K$, we have a left inverse L_K of K minimizing for A, a left inverse L_H of H, and $L_H L_K = L_{KH}$. In fact, L_H is minimizing for $C_K(A)$ since by Lemma 3

$$C_H$$
 is minimizing for $C_K(A)$ since by Lemma 0.

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The converse part is immediate: Evidently $L_H L_K$ is a left inverse of KH, and $L_H L_K A L'_K L'_H = L_H C_K (A) L'_H = C_H (C_K (A)) = C_{KH} (A).$

We shall now use these intermediate results for our discussion of admissibility and optimality.

4. ADMISSIBILITY FOR PARAMETER SUBSETS

Let $M\in\mathcal{M}$ be a fixed moment matrix. We resume the discussion of M being admission. sible for K' heta in M. Assume that $C_K(M)
eq 0$ and choose a full rank decomposition $C_K(M)=HH'$ as in Section 3. We first present a result similar to Lemma 1.

Lemma 5. Let $A \in M$ be a competing moment matrix. If A is E-optimal for $H'K'\theta$ in M then $C_K(A) \geq C_K(M)$.

Proof. By construction the range of $C_K(M)$ contains the range of H. Applying Lemma 3 we obtain

$$C_{KH}(M) = (H'C_K(M)^-H)^{-1} = (H'(HH')^-H)^{-1} = I_t.$$

Optimality of A yields $1 = \lambda_{\min}(C_{KH}(M)) \leq \lambda_{\min}(C_{KH}(A))$. Therefore $I_t \leq C_{KH}(A)$, and pre- and postmultiplication with H and H' yields

$$C_K(M) = HH' \le HC_H(C_K(A))H' \le C_K(A).$$

Note that $C_H(C_K(A)) = C_{KH}(A)$ is nonsingular and hence $C_K(A) \in \mathcal{A}(H)$.

The following theorem on admissibility and E-optimality parallels Theorem 1.

Theorem 3. The moment matrix M is admissible for $K'\theta$ in M if and only if M is E-optimal for $H'K'\theta$ in M and for any other E-optimal moment matrix $A \in M$ for $H'K'\theta$ in M we have $C_K(A) = C_K(M)$.

Proof. Follow the proof of Theorem 1, with Lemma 1 replaced by Lemma 5. Use Lemma 3 for the converse part.

We are now in a position to present our main result: A proof based on E-optimality of Theorem 2 of Gaffke (1987).

Theorem 4. (i) If M is admissible for $K'\theta$ in M then there exists a nonnegative definite $s \times s$ matrix $D \neq 0$ and there exists a left inverse L_K of K minimizing for M such that L'_KDL_K is normal to M at M.

(ii) If there exists a positive definite $s \times s$ matrix D and a left inverse L_K of K minimizing for M such that $L'_K DL_K$ is normal to M at M then M is admissible for $K'\theta$ in M.

Proof. (i) By Theorem 3 the moment matrix M is E-optimal for $H'K'\theta$ in M, and as shown above $C_{KH}(M) = I_t$. The general equivalence theory tells us that

$$\operatorname{trace}(H'K'GAG'KHE) \leq 1 \quad \text{for all } A \in \mathcal{M},$$

for some generalized inverse G of M and some nonnegative definite $t \times t$ matrix E with trace equal to 1. Define the matrix N = G'KHEH'K'G. Then

$$\operatorname{trace}(AN) \leq 1 = \operatorname{trace}(MN)$$
 for all $A \in M$,

and $1 \leq \operatorname{rank} N \leq t$. The matrix $L_{KH} = H'K'G$ satisfies $L_{KH}KH = H'K'GKH$ $= (C_{KH}(M))^{-1} = I_t$ and $L_{KH}ML'_{KH} = H'K'GMG'KH = I_t = C_{KH}(M)$, and thus is a left inverse of KH minimizing for M. Lemma 4 then ensures that $L_{KH} = L_HL_K$ where L_K is a left inverse of K minimizing for M. Setting $D = L'_HEL_H$ we obtain the desired representation

$$N = L'_{KH}EL_{KH} = L'_{K}L'_{H}EL_{H}L_{K} = L'_{K}DL_{K}.$$

(ii) Let A be a competing moment matrix satisfying $C_K(A) \geq C_K(M)$. Then

$$egin{aligned} 0 &\leq \operatorname{trace}\left\{\left(C_K(A) - C_K(M)\right)D
ight\} \ &\leq \operatorname{trace}\left\{\left(L_KAL_K' - L_KML_K'\right)D
ight\} \ &= \operatorname{trace}\left\{\left(A - M\right)L_K'DL_K
ight\} \leq 0, \end{aligned}$$

and because of positive definiteness of D therefore $C_K(A) = C_K(M)$.

The proof gives the additional information that in Theorem 4(i) we can choose the $s \times s$ matrix D so as to satisfy $1 \le \operatorname{rank} D \le t = \operatorname{rank} C_K(M)$.

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Lecture Notes in Economics and Mathematical Systems

Managing Editors: M. Beckmann and W. Krelle

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V. Fedorov H. Läuter (Eds.)

Model-Oriented Data Analysis

Proceedings of an IIASA (International Institute for Applied Systems Analysis) Workshop on Data Analysis Held at Eisenach, GDR, March 9-13, 1987



Springer-Verlag 1988

Berlin Heidelberg New York London Paris Tokyo